

# Servo amplifier

## mcDSA-F55

Article number: 1511722



Picture similar

**Technical data**

<b>Absolute maximum rating (destruction limits)</b>		<b>Sensor supply (Encoder/Hall)</b>
Power supply voltage Up no polarity reversal protection	70 V	Output voltage 5 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	Max. output current 0.2 A
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	<b>Incremental encoder</b>
<b>Power</b>		Type incremental
Electronic supply voltage Ue	9..30 V	Signals A./A,B./B,Inx
Electronic current consumption@ Ue=24V*1	typ. 60 mA	Max. frequency (per channel) 500 kHz
Power supply voltage Up	9..60 V	Input voltage (24V tolerant) 0.5 V
Max. output current	50 A	Signal type differential, open collector, single ended
Continuous output current*2	12.5 A	<b>Hall sensors</b>
<b>PWM</b>		Signals H1,H2,H3
PWM frequency	32 kHz	Max. frequency (per channel) 10 kHz
<b>Mechanical</b>		Input voltage 0.5 V
Size LxWxH	78 x 74 x 29 mm	Signal type open collector, single ended
Weight	95 g	<b>Digital inputs</b>
<b>Environment</b>		Number - digital inputs 6 (Din0..5)
Protection class	IP20	Number - hardware enable inputs 2 (EN-A..B)
Ambient temperature (operation)*3	-40..70 °C	Low voltage 0.5 V
Ambient temperature (storage)	-40..85 °C	High voltage 8..30 V
Rel. humidity (non-condensing)	5..90 %	<b>Digital outputs</b>
<b>CAN bus</b>		Number 4 (Dout0..3)
Protocol	DS301	Continuous output current 0.3 A
Device profile	DS402	Load resistive, inductive
Max. baudrate	1 Mbit/s	Output voltage Electronic supply voltage Ue
CAN specification	2.0B	Signal type positive switching
Galvanically isolated	yes	<b>Analog inputs</b>
		Number 3 (Ain0..2)
		Signal type - Ain0..1 +/- 10 V, 12 Bit, differential
		Signal type - Ain2 0..5 V, 12 Bit, single ended

\*1 power amplifier switched off, 5V output (sensor supply) is free

\*2 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t &gt; 40 °C derating), RMS current: 12.5 A → 8.8 Aeff no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

\*3 Hex-Switches should be not used at T &lt; -25°C (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.



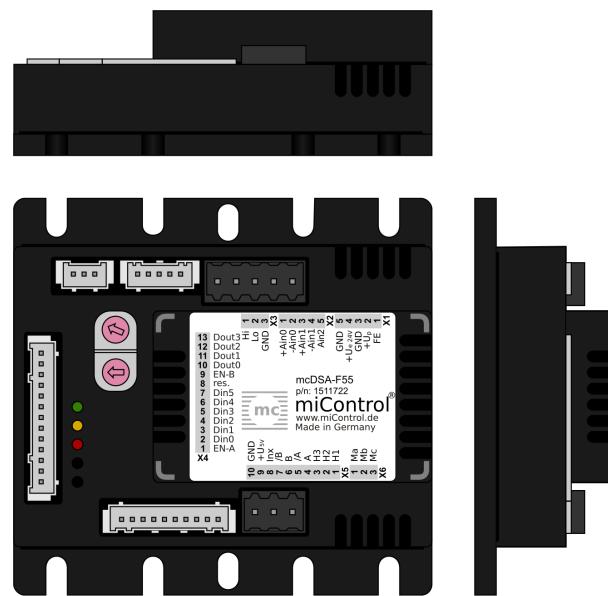
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## Scheme



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## Terminal assignment

X1 Supply		
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	+Ue24V	Electronic supply voltage
5	GND	Ground for electronic supply voltage

X2 Analog inputs		
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V)

X3 CAN bus		
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	CAN GND	CAN Ground

X4 Digital inputs/outputs		
1	EN-A	Hardware enable channel A
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	res.	Reserved
9	EN-B	Hardware enable channel B
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5 Hall and inc. encoder		
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder, A channel
5	/A	Inc. encoder, A channel inverted
6	B	Inc. encoder, B channel
7	/B	Inc. encoder, B channel inverted
8	Inx	Inc. encoder, index channel
9	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
10	GND	Ground for sensor supply Notice: don't connect with system GND

Motor		
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C