

Servo amplifier

mcDSA-E57-PN-HC

Article number: 1514629



Picture similar

Technical data

Absolute maximum rating (destruction limits)		PROFINET		
Power supply voltage Up no polarity reversal protection	80 V	Type	Slave	
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	Physical layer	100 Base-Tx	
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	Max. baudrate	100 Mbit/s	
Power			Number of ports	
Electronic supply voltage Ue	9..30 V	Sensor supply (Encoder)	2xRJ45 (PORT1, PORT2)	
Electronic current consumption@ Ue=24V*1	typ. 85 mA	Output voltage	5 V	
Power supply voltage Up	9..60 V	Max. output current	0.2 A	
Max. output current	50 A	Encoder		
Continuous output current*2	14.5 A	Type	sin / cos	
PWM			Signals	
Output voltage	100% Up	+Sin,-Sin,+Cos,-Cos		
PWM frequency	25, 32*3, 50 kHz	Resolution	13 bit per sine period	
Mechanical			Input voltage	
Size LxWxH	87 x 74 x 49 mm		1 V peak-peak, differential	
Weight	226 g	Signal type	sine/cosine, analog, differential	
Environment			Digital inputs	
Protection class	IP20	Number - digital inputs	8 (Din0..7)	
Ambient temperature (operation)	-40..70 °C	Low voltage	0.5 V	
Ambient temperature (storage)	-40..85 °C	High voltage	8..30 V	
Rel. humidity (non-condensing)	5..90 %	Digital outputs		
CAN bus			Number	
Protocol	DS301	Continuous output current	0.3 A	
Device profile	DS402	Load Dout0..2	resistive, low inductive	
Max. baudrate	1 Mbit/s	Load Dout3	resistive, inductive	
CAN specification	2.0B	Output voltage	Electronic supply voltage Ue	
Galvanically isolated	no	Signal type	positive switching	
Analog inputs			Analog inputs	
		Number	3 (Ain0..2)	
		Signal type - Ain0..1	+/- 10 V, 12 Bit, differential	
		Signal type - Ain2	0..5 V, 12 Bit, single ended	

*1 power amplifier switched off, 5V output (sensor supply) is free, bus not connected

*2 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C ($t > 40$ °C derating), RMS current: 14.5 A → 11.8 Aeff
no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*3 default value

Additional technical data are available in mcManual.



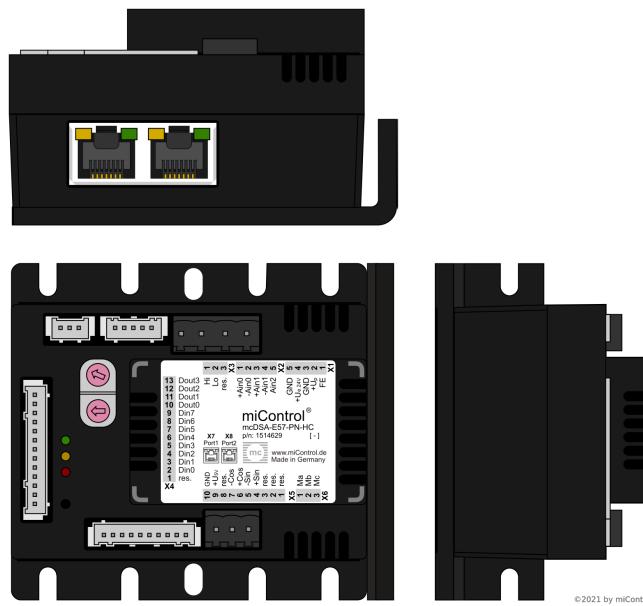
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Scheme



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Terminal assignment

X1 Supply		
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	+Ue24V	Electronic supply voltage
5	GND	Ground for electronic supply voltage
X2 Analog inputs		
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V)
X3 CAN bus		
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	res.	Reserved
X4 Digital inputs/outputs		
1	res.	Reserved
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	Din7	Digital input 7
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5 Encoder		
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	-Sin	Encoder, minus sine signal
6	+Cos	Encoder, plus cosine signal
7	-Cos	Encoder, minus cosine signal
8	res.	Reserved
9	+U5V	5V output voltage for sensor supply Sensors: encoder
10	GND	Ground for sensor supply Notice: don't connect with system GND
X6 Motor		
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C
X7 PROFINET - PORT1		
-	PORT1	PORT1
X8 PROFINET - PORT2		
-	PORT2	PORT2