

Servo amplifier

mcDSA-E57-Lp

Article number: 1514035

Certification:  *1
E475093



Picture similar

Technical data

Absolute maximum rating (destruction limits)		Sensor supply (Encoder)
Power supply voltage Up no polarity reversal protection	80 V	Output voltage 5 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	Max. output current 0.2 A
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	
Power		Encoder
Electronic supply voltage Ue	9..30 V	Type sin / cos
Electronic current consumption@ Ue=24V*2	typ. 40 mA	Signals +Sin,-Sin,+Cos,-Cos
Power supply voltage Up	9..60 V	Resolution 13 bit per sine period
Max. output current	50 A	Input voltage 1 V peak-peak, differential
Continuous output current @ Up=24V*3	10 A	Signal type sine/cosine, analog, differential
Continuous output current @ Up=48V*3	10 A	
Continuous output current (certified UL)*4 @Up=24V	9.5 A	Digital inputs
@Up=60V	9 A	Number - digital inputs 8 (Din0..7)
		Low voltage 0.5 V
		High voltage 8..30 V
PWM		Digital outputs
Output voltage	100% Up	Number 4 (Dout0..3)
PWM frequency	25, 32*5, 50 kHz	Continuous output current (certified UL) 0.3 A
Mechanical		Continuous output current (not certified) 0.3 A
Size LxWxH	70 x 50 x 19 mm	Load Dout0..2 resistive, low inductive
Weight	50 g	Load Dout3 resistive, inductive
Environment		Output voltage Electronic supply voltage Ue
Protection class	IP00	Signal type positive switching
Ambient temperature (operation) (certified UL)	-40..40 °C	
Ambient temperature (operation) (not certified)	-40..70 °C	Analog inputs
Ambient temperature (storage)	-40..85 °C	Number 3 (Ain0..2)
Rel. humidity (non-condensing)	5..90 %	Signal type - Ain0..1 +/- 10 V, 12 Bit, differential
CAN bus		Signal type - Ain2 / PT1000 0.5 V, 12 Bit, single ended / PT1000
Protocol	DS301	
Device profile	DS402	
Max. baudrate	1 Mbit/s	
CAN specification	2.0B	
Galvanically isolated	no	

*1 The certified performance data must be observed (see UL Instruction Note)

*2 power amplifier switched off, 5V output (sensor supply) is free

*3 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t > 40 °C derating), RMS current: 10 A → 8.2 Aeff no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*4 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output active, RMS current: 9.5 A → 7.8 Aeff, 9 A → 7.3 Aeff

*5 default value

Additional technical data are available in mcManual.



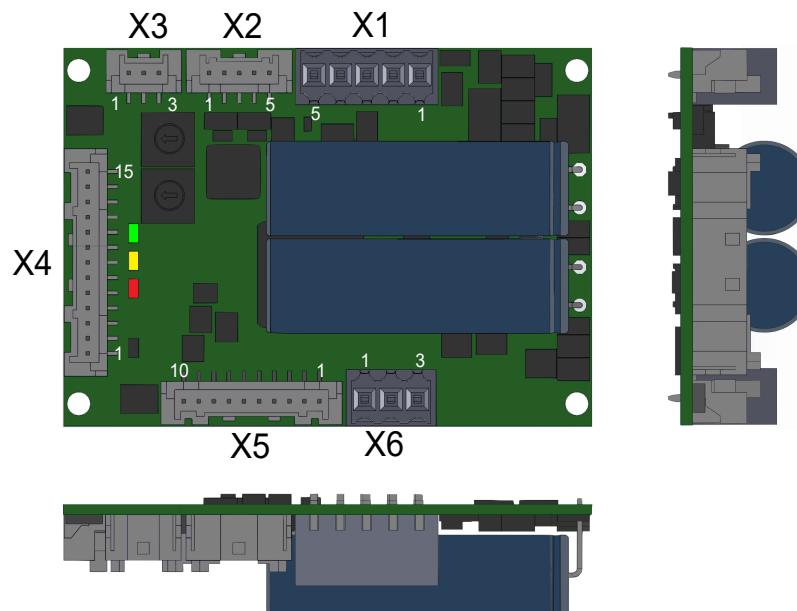
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Scheme



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Terminal assignment

X1 Supply		
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	+Ue24V	Electronic supply voltage
5	GND	Ground for electronic supply voltage

X2 Analog inputs		
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V) / PT1000

X3 CAN bus		
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	res.	Reserved

X4 Digital inputs/outputs		
1	res.	Reserved
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	Din7	Digital input 7
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5 Encoder		
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	-Sin	Encoder, minus sine signal
6	+Cos	Encoder, plus cosine signal
7	-Cos	Encoder, minus cosine signal
8	res.	Reserved
9	+U5V	5V output voltage for sensor supply Sensors: encoder
10	GND	Ground for sensor supply Notice: don't connect with system GND

X6 Motor		
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C