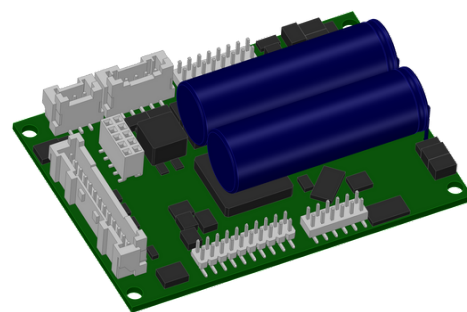


Servo amplifier

mcDSA-E56-Modul

Article number: 1514033

 Certification:  **US** *1
E475093


Picture similar

Technical data

Supply voltages	
Electronic supply voltage Ue*2	9..30 V
Electronic current consumption@ Ue=24V*3	typ. 40 mA
Power supply voltage Up*4	9..60 V
Output current	
Max. output current	50 A
Continuous output current (certified UL)*5	
@Up ≤ 24V	9.5 A
@Up ≤ 60V	9 A
Continuous output current (not certified)*6	
@Up ≤ 24V	10 A
@Up ≤ 48V	10 A
PWM	
Output voltage	100% Up
PWM frequency	25, 32*7, 50 kHz
Mechanical	
Size LxWxH	70 x 50 x 18 mm
Weight	50 g
Environment	
Protection class	IP00
Ambient temperature (operation) (certified UL)	-40..40 °C
Ambient temperature (operation) (not certified)	-40..70 °C
Ambient temperature (storage)	-40..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no
Sensor supply (Hall)	
Output voltage	5 V
Max. output current	0.2 A

Encoder	
Type	magnetic sensor
Signals	A, B channels internally
Resolution	12 bit per motor shaft revolution
Signal type	Magnetic sensor with magnet on the motor shaft
Hall sensors	
Signals	H1,H2,H3
Max. frequency (per channel)	10 kHz
Input voltage	0..5 V
Signal type	open collector, single ended
Digital inputs	
Number - digital inputs	8 (Din0..7)
Low voltage	0..5 V
High voltage	8..30 V
Digital outputs	
Number	4 (Dout0..3)
Continuous output current (certified UL)	0.3 A
Continuous output current (not certified)	0.3 A
Load Dout0..2	resistive, low inductive
Load Dout3	resistive, inductive
Output voltage	Electronic supply voltage Ue
Signal type	positive switching
Analog inputs	
Number	3 (Ain0..2)
Signal type - Ain0..1	+/- 10 V, 12 Bit, differential
Signal type - Ain2 / PT1000	0..5 V, 12 Bit, single ended / PT1000

*1 The certified performance data must be observed (see UL Instruction Note)

*2 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 33V$ or short-term peak voltage of $37V < 1s$

*3 power amplifier switched off, 5V output (sensor supply) is free

*4 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 80V$ *5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output active, RMS current: 9.5 A $\rightarrow$ 7.8 Aeff, 9 A $\rightarrow$ 7.3 Aeff*6 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output free, RMS current: 10 A $\rightarrow$ 8.2 Aeff, 10 A $\rightarrow$ 8.2 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*7 default value

Additional technical data are available in mcManual.



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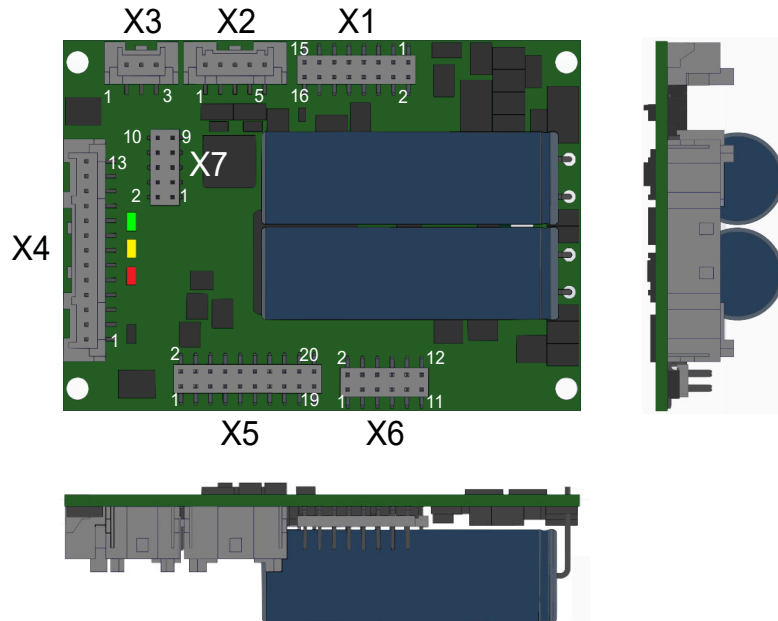
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mcDSA-E56-Modul - PV1.13.00.00 / DV1.00.00.07

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Scheme



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Terminal assignment

X1 Supply		
1	FE	Functional earth
2	FE	Functional earth
3	+Up	Power supply voltage
4	+Up	Power supply voltage
5	+Up	Power supply voltage
6	+Up	Power supply voltage
7	GND	Ground for power supply voltage
8	GND	Ground for power supply voltage
9	GND	Ground for power supply voltage
10	GND	Ground for power supply voltage
11	+Ue24V	Electronic supply voltage
12	+Ue24V	Electronic supply voltage
13	GND	Ground for electronic supply voltage
14	GND	Ground for electronic supply voltage
15	GND	Ground for electronic supply voltage
16	GND	Ground for electronic supply voltage
X2 Analog inputs		
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V) / PT1000
X3 CAN bus		
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	res.	Reserved
X4 Digital inputs/outputs		
1	res.	Reserved
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	Din7	Digital input 7
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5 Hall and inc. encoder		
1	res.	Reserved
2	GND	Ground for sensor supply Notice: don't connect with system GND
3	Erw5	mcSPI expansion signal 5
4	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
5	Erw3	mcSPI expansion signal 3
6	res.	Reserved
7	Erw4	mcSPI expansion signal 4
8	res.	Reserved
9	SpiMISO	mcSPI Master In
10	res.	Reserved
11	Spi/SS	mcSPI Slave Select
12	res.	Reserved
13	SpiMOSI	mcSPI Master Out
14	res.	Reserved
15	SpiCLK	mcSPI Clock
16	H3	Hall sensor 3
17	Erw1	mcSPI expansion signal 1
18	H2	Hall sensor 2
19	Erw2	mcSPI expansion signal 2
20	H1	Hall sensor 1
X6 Motor		
1	Ma	Motor phase A
2	Ma	Motor phase A
3	Ma	Motor phase A
4	Ma	Motor phase A
5	Mb	Motor phase B
6	Mb	Motor phase B
7	Mb	Motor phase B
8	Mb	Motor phase B
9	Mc	Motor phase C
10	Mc	Motor phase C
11	Mc	Motor phase C
12	Mc	Motor phase C

Terminal assignment

X7	Node ID	
1	/Id6	Node-ID Bit 6 inverted
2	/Id5	Node-ID Bit 5 inverted
3	/Id7	Node-ID Bit 7 inverted
4	/Id4	Node-ID Bit 4 inverted
5	GND	Ground
6	GND	Ground
7	/Id2	Node-ID Bit 2 inverted
8	/Id1	Node-ID Bit 1 inverted
9	/Id3	Node-ID Bit 3 inverted
10	/Id0	Node-ID Bit 0 inverted

