

# Servo amplifier

## mcDSA-E55-Lp

Article number: 1514030


**\*1**  
E475093


Picture similar

**Technical data**

<b>Supply voltages</b>		<b>Incremental encoder</b>	
Electronic supply voltage Ue* <sup>2</sup>	9..30 V	Type	incremental
Electronic current consumption@ Ue=24V* <sup>3</sup>	typ. 40 mA	Signals	A,/A,B,/B,Inx
Power supply voltage Up* <sup>4</sup>	9..60 V	Max. frequency (per channel)	500 kHz
<b>Output current</b>		Input voltage	0..5 V
Max. output current	50 A	Signal type	differential, open collector, single ended
Continuous output current (certified UL)* <sup>5</sup> @Up ≤ 24V	9.5 A	<b>Hall sensors</b>	
@Up ≤ 60V	9 A	Signals	H1,H2,H3
Continuous output current (not certified)* <sup>6</sup> @Up ≤ 24V	10 A	Max. frequency (per channel)	10 kHz
@Up ≤ 48V	10 A	Input voltage	0..5 V
<b>PWM</b>		Signal type	open collector, single ended
Output voltage	100% Up	<b>Digital inputs</b>	
PWM frequency	25, 32* <sup>7</sup> , 50 kHz	Number - digital inputs	8 (Din0..7)
<b>Mechanical</b>		Low voltage	0..5 V
Size LxWxH	70 x 50 x 19 mm	High voltage	8..30 V
Weight	50 g	<b>Digital outputs</b>	
<b>Environment</b>		Number	4 (Dout0..3)
Protection class	IP00	Continuous output current (certified UL)	0..3 A
Ambient temperature (operation) (certified UL)	-40..40 °C	Continuous output current (not certified)	0..3 A
Ambient temperature (operation) (not certified)	-40..70 °C	Load Dout0..2	resistive, low inductive
Ambient temperature (storage)	-40..85 °C	Load Dout3	resistive, inductive
Rel. humidity (non-condensing)	5..90 %	Output voltage	Electronic supply voltage Ue positive switching
<b>CAN bus</b>		<b>Analog inputs</b>	
Protocol	DS301	Number	3 (Ain0..2)
Device profile	DS402	Signal type - Ain0..1	+/- 10 V, 12 Bit, differential
Max. baudrate	1 Mbit/s	Signal type - Ain2 / PT1000	0..5 V, 12 Bit, single ended / PT1000
CAN specification	2.0B		
Galvanically isolated	no		
<b>Sensor supply (Encoder/Hall)</b>			
Output voltage	5 V		
Max. output current	0.2 A		

\*1 The certified performance data must be observed (see UL Instruction Note)

\*2 No reverse polarity protection, the destruction limit is at overvoltage of &gt;= 33V or short-term peak voltage of 37V &lt; 1s

\*3 power amplifier switched off, 5V output (sensor supply) is free

\*4 No reverse polarity protection, the destruction limit is at overvoltage of &gt;= 80V

\*5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output active, RMS current: 9.5 A → 7.8 Aeff, 9 A → 7.3 Aeff

\*6 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output free, RMS current: 10 A → 8.2 Aeff, 10 A → 8.2 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

\*7 default value

Additional technical data are available in mcManual.



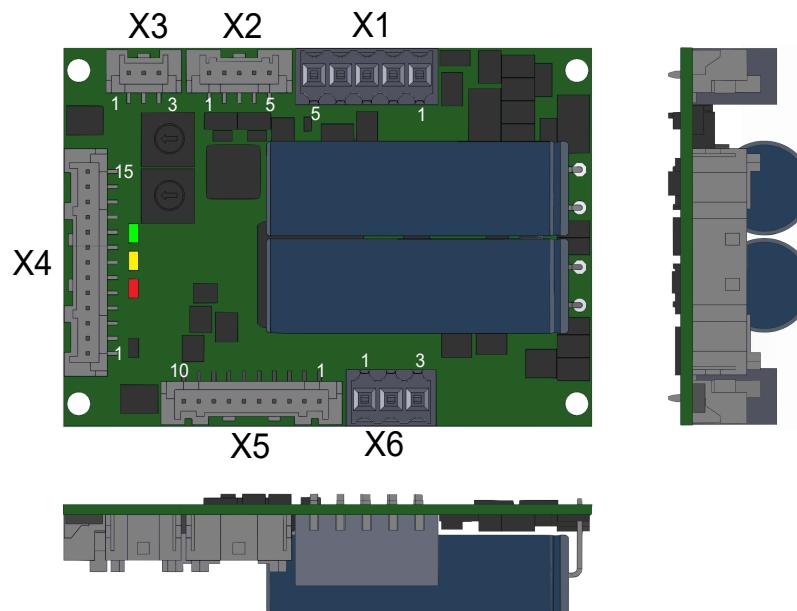
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## Scheme



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## Terminal assignment

X1 Supply		
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	+Ue24V	Electronic supply voltage
5	GND	Ground for electronic supply voltage
X2 Analog inputs		
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V) / PT1000
X3 CAN bus		
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	res.	Reserved
X4 Digital inputs/outputs		
1	res.	Reserved
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	Din7	Digital input 7
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5 Hall and inc. encoder		
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder, A channel
5	/A	Inc. encoder, A channel inverted
6	B	Inc. encoder, B channel
7	/B	Inc. encoder, B channel inverted
8	Inx	Inc. encoder, index channel
9	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
10	GND	Ground for sensor supply Notice: don't connect with system GND
X6 Motor		
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C