

Servo amplifier

mcDSA-E45-PROFINET

Article number: 1515607

Certification:  *1
E475093



Picture similar

Technical data

Supply voltages		PROFINET	
Electronic supply voltage Ue* ²	9..30 V	Type	Slave
Electronic current consumption@ Ue=24V* ³	typ. 100 mA	Physical layer	100 Base-Tx
Power supply voltage Up* ⁴	9..60 V	Max. baudrate	100 Mbit/s
Output current		Number of ports	
Max. output current	50 A	2xRJ45 (PORT1, PORT2)	
Continuous output current (certified UL)* ⁵ @Up ≤ 24V	10 A	Output voltage	5 V
@Up ≤ 60V	8 A	Max. output current	0.2 A
Continuous output current (not certified)* ⁶ @Up ≤ 24V	10 A	Incremental encoder	
@Up ≤ 48V	8.5 A	Type	incremental
PWM		Signals	A,/A,B,/B,Inx,/Inx
Output voltage	100% Up	Max. freqency (per channel)	500 kHz
PWM frequency	25, 32* ⁷ , 50 kHz	Input voltage (24V tolerant)	0..5 V
Mechanical		Signal type	differential, open collector, single ended
Size LxWxH	110 x 45 x 77 mm	Hall sensors	
Weight	170 g	Signals	H1,/H1,H2,/H2,H3,/H3
Environment		Max. freqency (per channel)	10 kHz
Protection class	IP20	Input voltage (24V tolerant)	0..5 V
Ambient temperature (operation)* ⁸ (certified UL)	-40..40 °C	Signal type	differential, open collector, single ended
Ambient temperature (operation)* ⁸ (not certified)	-40..70 °C	Digital inputs	
Ambient temperature (storage)	-40..85 °C	Number - digital inputs	8 (Din0..7)
Rel. humidity (non-condensing)	5..90 %	Low voltage	0..5 V
CAN bus		High voltage	8..30 V
Protocol	DS301	Digital outputs	
Device profile	DS402	Number	2 (Dout0..1)
Max. baudrate	1 Mbit/s	Continuous output current (certified UL)	0.75 A
CAN specification	2.0B	Continuous output current (not certified)	1.5 A
Galvanically isolated	no	Load	resistive, inductive
		Output voltage	Electronic supply voltage Ue
		Signal type	positive switching
Analog inputs		Analog inputs	
		Number	2 (Ain0..1)
		Signal type - Ain0	+/- 10 V, 12 Bit, differential
		Signal type - Ain1	+/- 10 V, 12 Bit, single ended

*1 The certified performance data must be observed (see UL Instruction Note)

*2 No reverse polarity protection, the destruction limit is at overvoltage of >= 33V or short-term peak voltage of 37V < 1s

*3 power amplifier switched off, 5V output (sensor supply) is free, bus not connected

*4 No reverse polarity protection, the destruction limit is at overvoltage of >= 80V

*5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output active, RMS current: 10 A → 8.2 Aeff, 8 A → 6.5 Aeff

*6 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output free, RMS current: 10 A → 8.2 Aeff, 8.5 A → 6.9 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*7 default value

*8 Hex-Switches should be not used at T < -25°C (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.



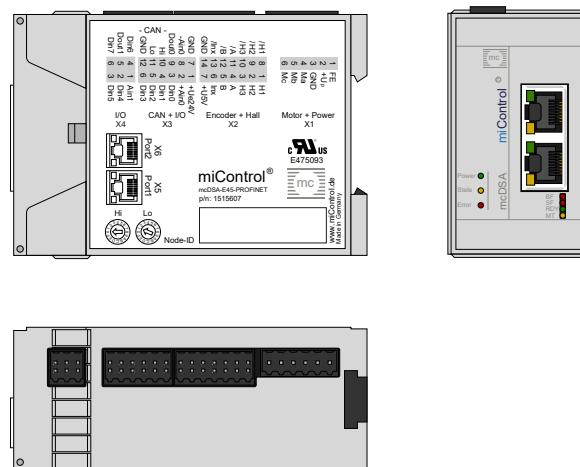
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Scheme



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Terminal assignment

X1	Motor	
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	Ma	Motor phase A
5	Mb	Motor phase B
6	Mc	Motor phase C
X2	Hall and inc. encoder	
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder, A channel
5	B	Inc. encoder, B channel
6	Inx	Inc. encoder, index channel
7	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
8	/H1	Hall sensor 1 inverted
9	/H2	Hall sensor 2 inverted
10	/H3	Hall sensor 3 inverted
11	/A	Inc. encoder, A channel inverted
12	/B	Inc. encoder, B channel inverted
13	/Inx	Inc. encoder, index channel inverted
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3	I/O's and CAN	
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground

X4	I/O's	
1	Ain1	Analog input 1
2	Din4	Digital input 4
3	Din5	Digital input 5
4	Din6	Digital input 6
5	Dout1	Digital output 1
6	Din7	Digital input 7
X5	PROFINET - PORT1	
-	PORT1	PORT1
X6	PROFINET - PORT2	
-	PORT2	PORT2