

Servo amplifier

mcDSA-E42-Lp

Article number: 1504953



Picture similar

Technical data

Absolute maximum rating (destruction limits)		Encoder
Power supply voltage Up no polarity reversal protection	80 V	Type sin / cos Signals +Sin,-Sin,+Cos,-Cos Resolution 13 bit per sine period Input voltage 1 V peak-peak, differential Signal type sine/cosine, analog, differential
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	
Power		Digital inputs
Electronic supply voltage Ue	9..30 V	Number 4 (Din0..3) Low voltage -30..5 V High voltage 6..30 V
Electronic current consumption@ Ue=24V*1	typ. 50 mA	Digital outputs
Power supply voltage Up	9..60 V	Number 1 (Dout0) Continuous output current 1.5 A Load resistive, inductive Output voltage Electronic supply voltage Ue Signal type positive switching
Max. output current	30 A	Analog inputs
Continuous output current @ Up=24V*2	10 A	Number 1 (Ain0) Signal type 0..10 V, 12 Bit, single ended
Continuous output current @ Up=48V*2	8.5 A	
PWM		
Output voltage	90% Up	
PWM frequency	25, 32*3, 50 kHz	
Mechanical		
Size LxWxH	97 x 73 x 14 mm	
Weight	58 g	
Environment		
Protection class	IP00	
Ambient temperature (operation)*4	-40..70 °C	
Ambient temperature (storage)	-40..85 °C	
Rel. humidity (non-condensing)	5..90 %	
CAN bus		
Protocol	DS301	
Device profile	DS402	
Max. baudrate	1 Mbit/s	
CAN specification	2.0B	
Galvanically isolated	no	

*1 power amplifier switched off, 5V output (sensor supply) is free

*2 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t > 40 °C derating), RMS current: 10 A → 8.2 Aeff, 8.5 A → 6.9 Aeff

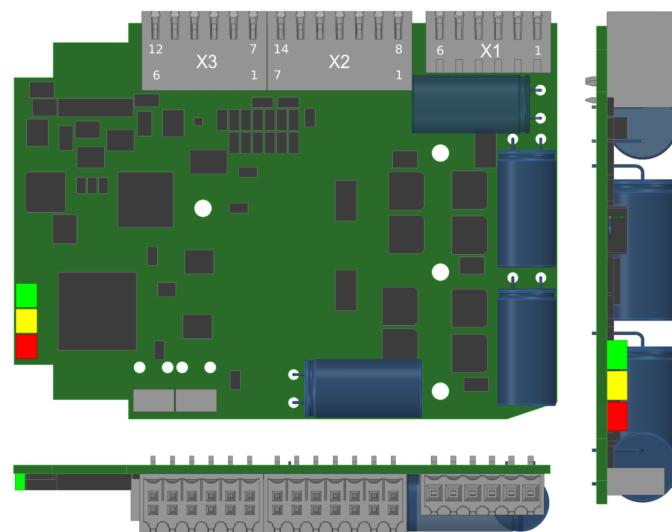
no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*3 default value

*4 Hex-Switches should be not used at T < -25°C (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.

Scheme



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Terminal assignment

X1 Motor		
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	Ma	Motor phase A
5	Mb	Motor phase B
6	Mc	Motor phase C

X2 Encoder		
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	+Cos	Encoder, plus cosine signal
6	res.	Reserved
7	+U5V	5V auxiliary voltage (encoder)
8	res.	Reserved
9	res.	Reserved
10	res.	Reserved
11	-Sin	Encoder, minus sine signal
12	-Cos	Encoder, minus cosine signal
13	res.	Reserved
14	GND	Ground for 5V auxiliary voltage (encoder)

X3 I/O's and CAN		
1	+Ue24V	Electronic supply voltage
2	Ain0	Analog input 0
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	res.	Reserved
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground